

# Tips on working: *Report and handling data*

Jens E. Wilhjelm

(with assistance by Sofie Rahbek and Mads Fjelbro Klavsen)

Biomedical Engineering Department of Health Technology

Biomedical Engineering DTU Health Technology

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 $f(x+\Delta x) = \sum_{i=0}^{\infty} \frac{(\Delta x)}{i!}$ 



- Directories with data and programs
- Example: Top photo
- Example: PET-CT
  - Fiducial markers in CT
  - PET data
- Report
- Various



#### Suggestion of structure of m-files, documents and data





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### A way to handle the top photo



HO 5/33



graphics and bitmapped images.



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### PET - CT





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#### PET - CT



Investigate voxel size in MATLAB!

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#### PET - CT



load Data; % PET data from fall 2007

sis\_extract\_axis\_info(Data);

	Arg 1	Arg 2	Arg 3	
Start of axis:	86.00000	40.00000	-5.73986 mm	
End of axis:	214.00000	210.00000	288.26015 mm	
Span of axis:	128.00000	170.00000	294.00001 mm	
Mean delta:	2.00000	2.00000	2.00000 mm	
Image size:	65	86	148 (i.	e.827320 voxels)

Maximum value:	32767.00000	?(6 voxels)
Mean value:	106.62967	?
Minimum value:	0.0000	?(519344 voxels)

"Arg" and "Dim" are used interchangeably.



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#### **Fiducial markers**



By use of sis\_zoom, you should extract an image that is positioned as indicated by the red frame.

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#### **Fiducial markers**



#### Phantom seen from the side





#### Phantom seen from the side





#### Phantom seen from the side







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#### **Example: Visualization of PET data**





(Photo from an older scanning)

# Example: Visualization of PET data "Collapsed" volumes





Arg1: 90 to 130 mn





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# Example: Visualization of PET data "Collapsed" volumes









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The electrical part of the measurement system is depicted in Fig. 2. The ultrasound system consisted of a pulser/receiver (type 5072PR, Panametrics, Inc., MA) connected to a submersible transducer (to be described in Subsection 2.1). The amplified signal from the pulser/receiver was bandpass filtered to limit noise outside the useable frequency range of the particular transducer and digitized with a digital storage oscilloscope (DSO) (type 9450, LeCroy, Genève, Switzerland). The DSO was in turn connected via a general purpose interface bus (GPIB) interface to a control computer running MS Windows. By means of an RS232 interface, a 3D translation system (type 403020, Dyrbæk Technologies, Åbenrå, Denmark) was connected to this control computer as well.



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#### **Borrowing from others**

(Photo removed)

#### Figure 1. Example of popular/unpopular behavior.

## What's "wrong" here?

- $I_{(xi)}$  Intensitet af medium (xi)  $[W/m^2]$
- $\Upsilon$  Gyromagnetisk ratio 42MHz/T for fotoner
- $\mu_m$  Lineær dæmpningskoefficient for pågældende voxel  $[m^{-1}]$
- μ Dæmpning
- μ Middelværdi
- $\lambda$  Bølgelængde [nm]
- <sup>18</sup>F Fluodeoxyglucose



#### Last, but not least...

 Write all the text yourself, or make citations with references

#### Keep

- reading the text book and
- writing your report

#### as two *seperate* tasks!

## Last, but not least...

Alternatives, that are *not* plagiarism:

- Write all the text yourself in your own words:
   → High grade, if correct.☺
- Write the text in a way that is close (but not identical) to the reference:
  - → Low grade. 😐
- Purely copy paste with citation marks and references:
  - → Very low grade. 🛞



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#### **Peer review**



Student 1	A1 08-09-16 (s061	).pdf 8. september 2016 21:26	<ul> <li>Student 14         <ul> <li>(s144 )</li> <li>Student 19<sup>(s144</sup> )</li> <li>Student 2</li></ul></li></ul>	
Student 2	Assignment_1.pdf	8. september 2016 22:09	<pre>✓ (s136 ) ✓ (s144 ) ✓ (s144 )</pre>	
Student 3	Assignment A1.pdf	8. september 2016 22:26	<ul> <li>✓</li> <li>(s123 )</li> <li>✓</li> <li>(s136 )</li> <li>✓</li> <li>(s144 )</li> </ul>	

	Student 14	Student 19	Student 2	
Purpose	Θ	Θ	<b>e</b>	
Method	<b>e</b>	e	•	
Processing of image	<del>()</del>	Θ	•	
Axes	Θ	e	e	
Fiducial markers	•	Θ	Θ	
Additional fiducial markers	<b>e</b>	<b>e</b>	•	
Geometry	Θ	e	Θ	
Zero point	Θ	<del>()</del>	•	
MATLAB code	e	Θ	Θ	
		•	•	

#### (The two figures here are from different data sets)

Se uddybende

begrundelser Se uddybende

begrundelser Se uddybende

begrundelser Se uddybende

begrundelser

Se uddybende

begrundelser

Se uddybende

begrundelser

Se uddybende

begrundelser Se uddybende

begrundelser Se uddybende

begrundelser Se uddybende begrundelser



#### draw\_fiducials\_on\_phantom;

- plot( bla)
- circle( bla)
- draw\_fiducials\_on\_phantom( Data, FiducialPoints, etc);

Δ1

- sis\_view( Data);
- plot( bla)
- circle( bla)